

# Programming Smart Buildings with Knowledge Graphs

*Playground* Tutorial

SenSys 2025

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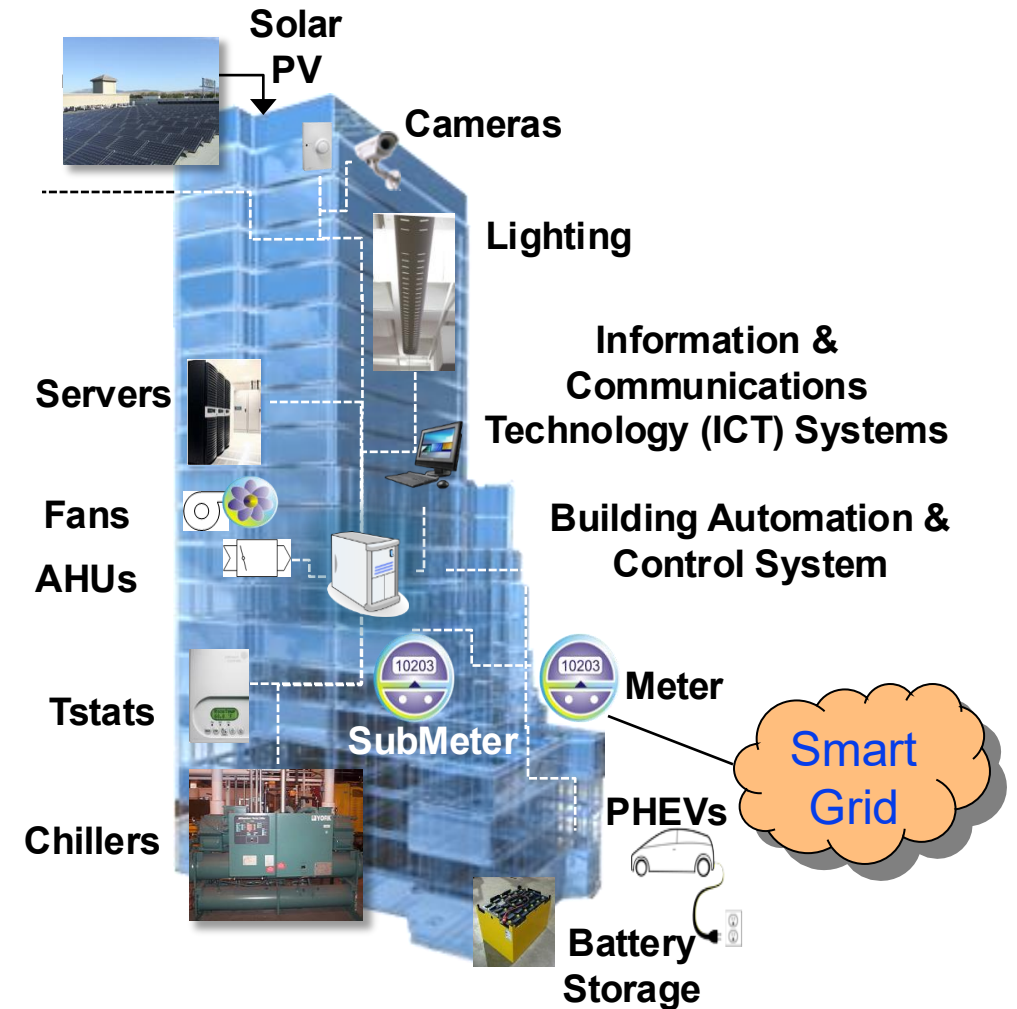
Joint Appointment @ NREL

# Outline

- Why we want to program buildings
- Why is programming buildings difficult?
- Addressing data discovery with knowledge graphs
- Programming smart buildings with knowledge graphs
- Specification-driven development

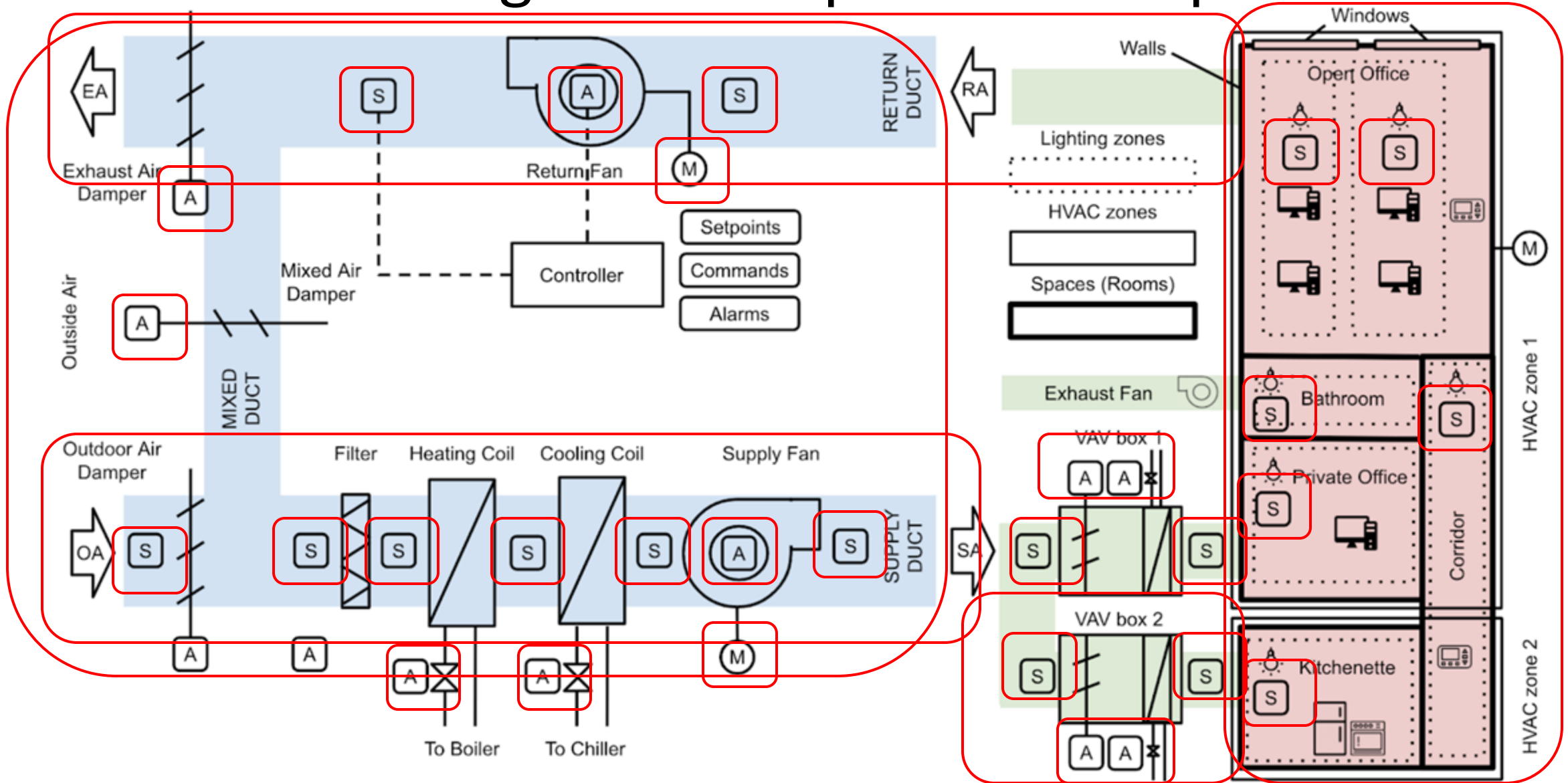
# Setting the Stage

- Modern buildings have large digital control/sensing surfaces
- Building management is increasingly complex and software driven
  - Renewables → bi-directional power flow
  - Dynamic energy/power tariffs
  - Personalized comfort settings
  - Advanced controls and fault detection
- **Adoption of “smart” software lags adoption of the hardware** (CBECS 2018)



**Why is it difficult to build smart building software?**

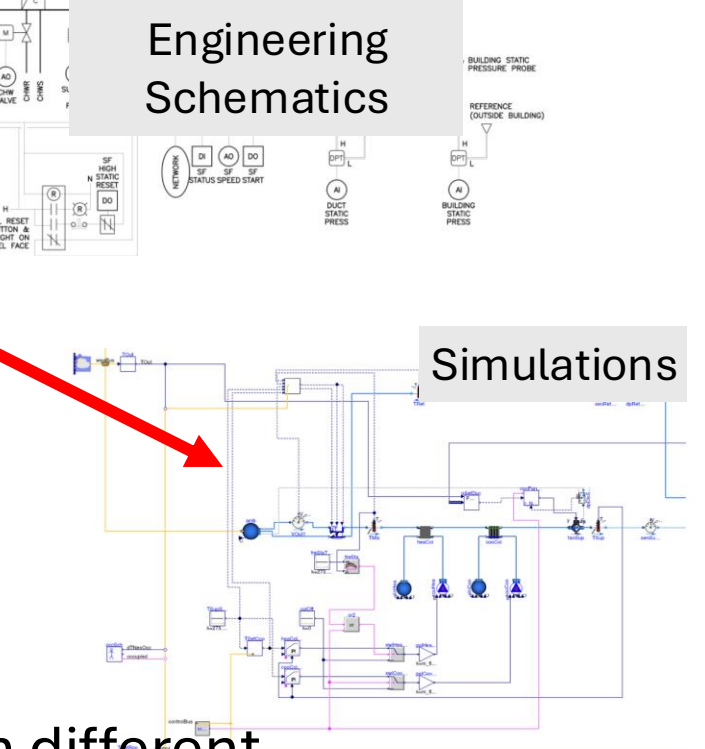
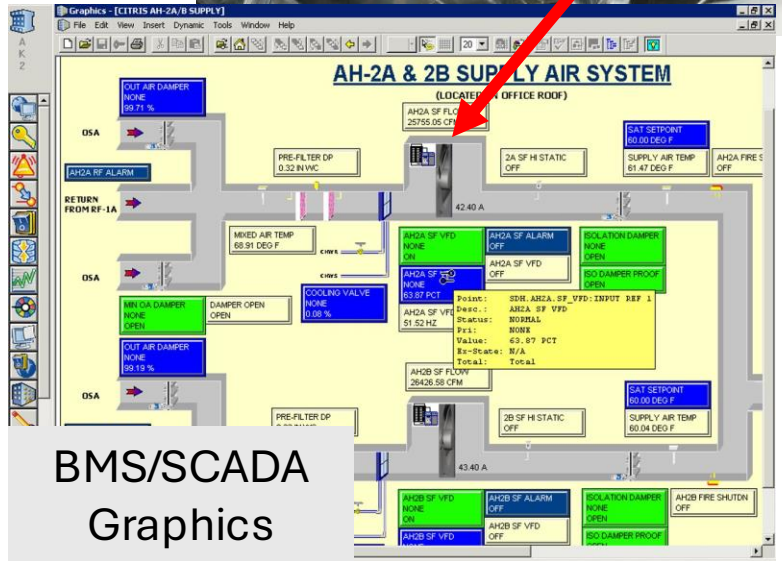
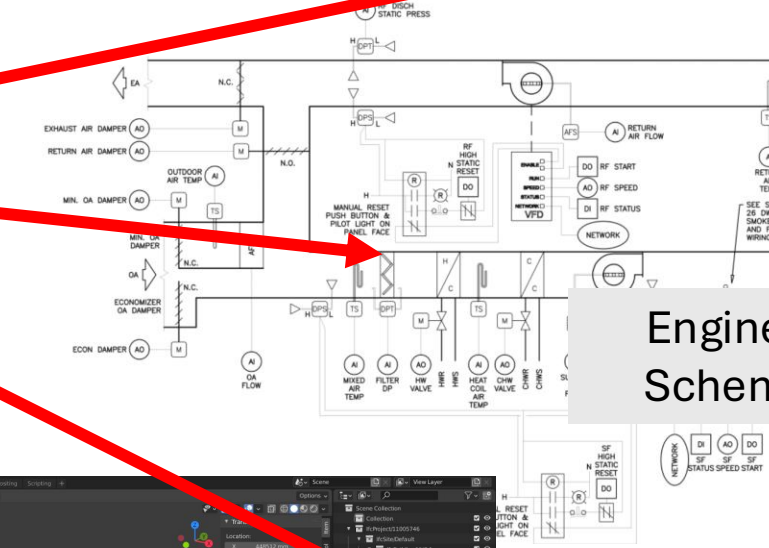
# Reason 1: Buildings are Complex and Bespoke CPS



**Not just home automation:** simple HVAC system for a commercial office building

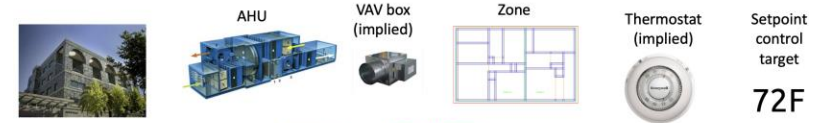
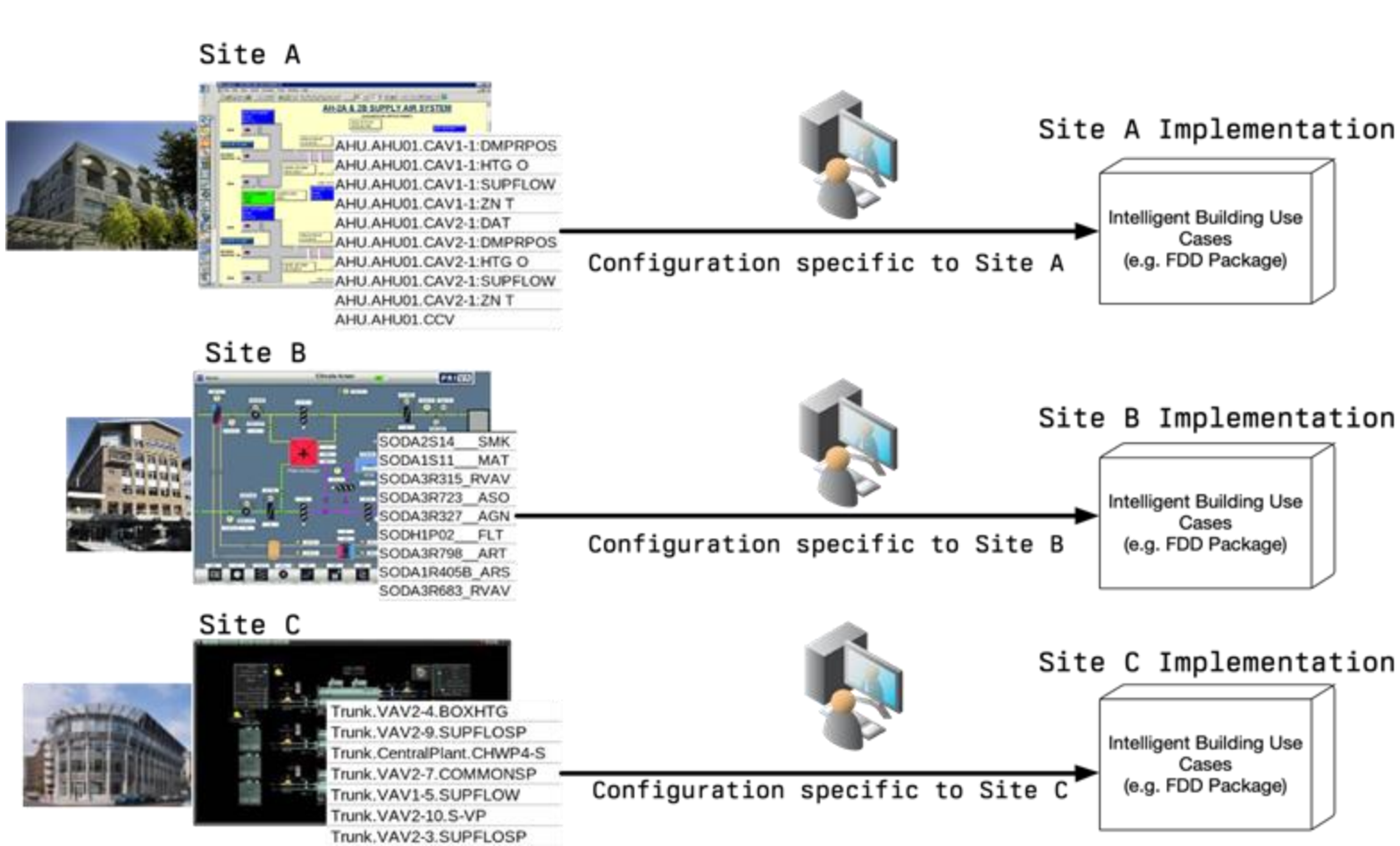
# Reason 2: Disconnected Digital Models

Field  
Controllers / PLC



Finding data often requires cross-referencing between different representations of the same system

# Reason 3: Each Building is Unique



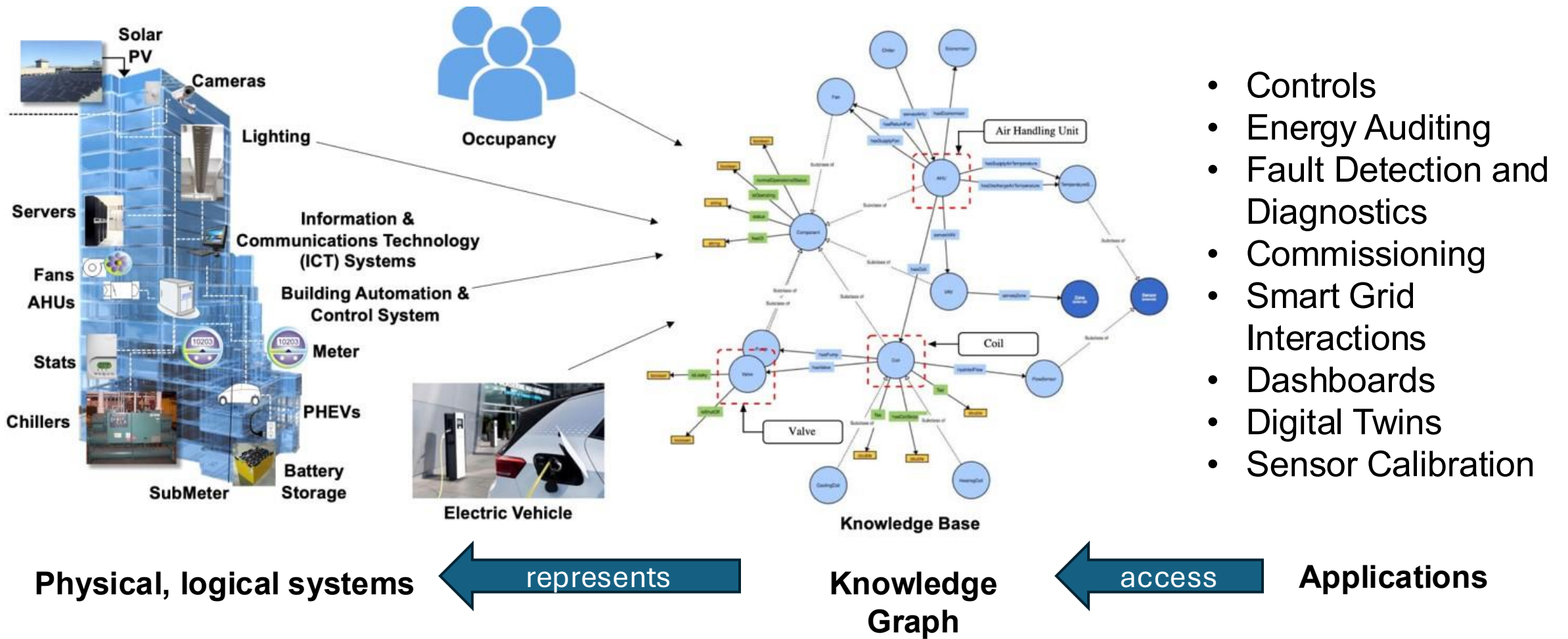
SODA1R465 ARS

Site name      Air Handling Unit      Zone/Room      Padding / delimiter      Zone Air Temperature Setpoint

**Naming conventions and protocol “soup”**



- Lack of standardization, interoperability increases soft costs associated with developing and deploying data-driven solutions



Two parts to solution:

- **Knowledge graphs:** a shared representation of devices, data sources, and environment
- **Portable programming models:** new ways of expressing data-driven logic using KGs



# The Brick Ontology

- Created in 2016 by researchers in the BuildSys community
- Standardizes names, definitions of common building assets, architectural elements, data sources
- Now a 501(c)(6) with 7 industrial partners



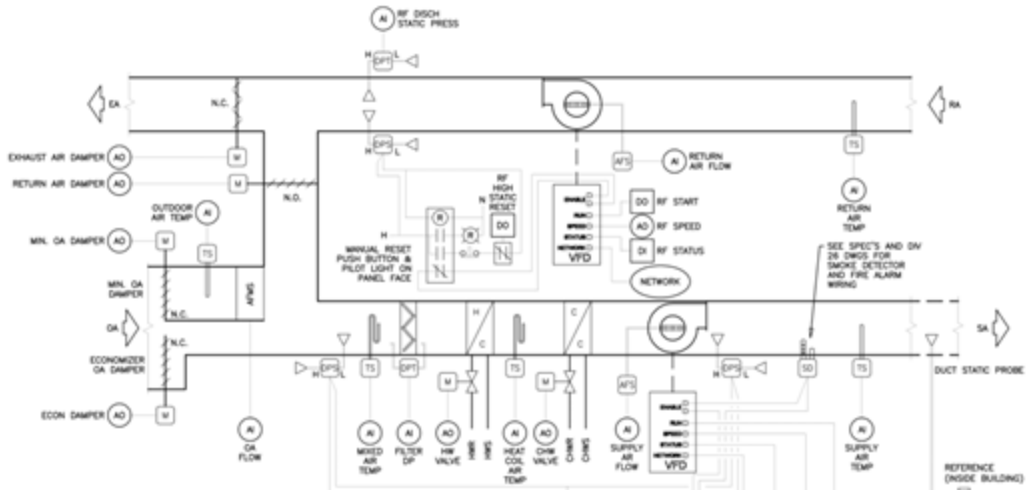
<https://brickschema.org>



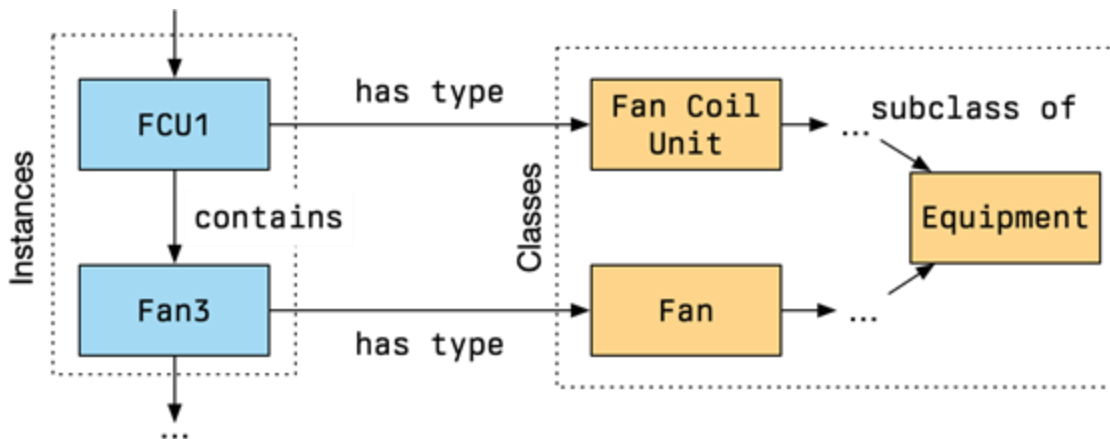
The screenshot shows the Brick Ontology web interface. At the top, there is a search bar and a dropdown menu for 'Select Brick version:' set to 'Brick v1.4'. Below this are tabs for 'Classes', 'Properties', and 'Ontologies'. The 'Classes' tab is active, showing a tree view of classes. The 'Point' class is selected, and its definition is displayed in the 'Definition' panel. The definition shows that 'Point' is a subclass of 'Class' and has several properties and relationships.

```
class brick Point extends brick Class
{
  * brick aggregate bsh AggregationShape;
  * brick electricalComplexPower bsh ElectricalComplexPowerShape;
  * brick electricalFlow bsh ElectricalFlowShape;
  0 brick hasLocation owl Thing;
  * brick hasQuantity ( qudt QuantityKind | rdfs Resource | brick Quantity )
  * brick hasSubstance ( rdfs Resource | brick Substance )
  * brick hasUnit qudt Unit;
  * brick isPointOf ( brick Equipment | brick Location (deprecated) | rec Space )
```

# Building on Open Standards for Semantic Metadata Graphs



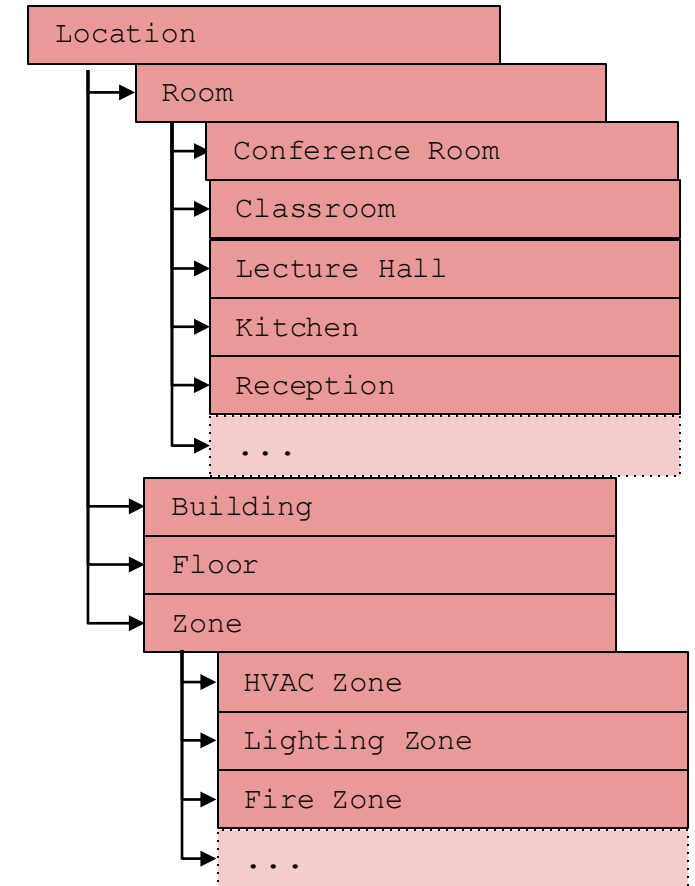
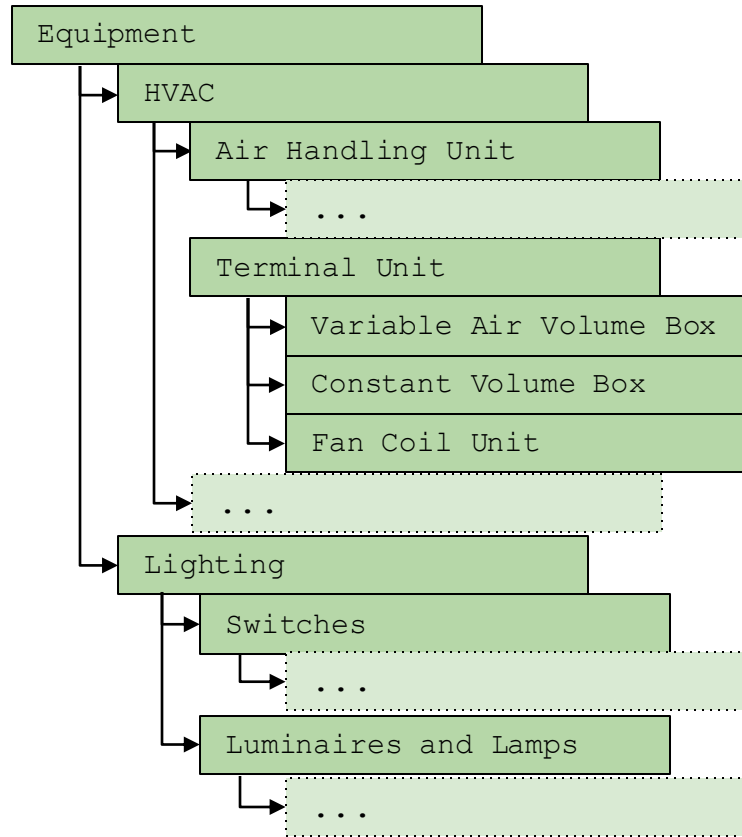
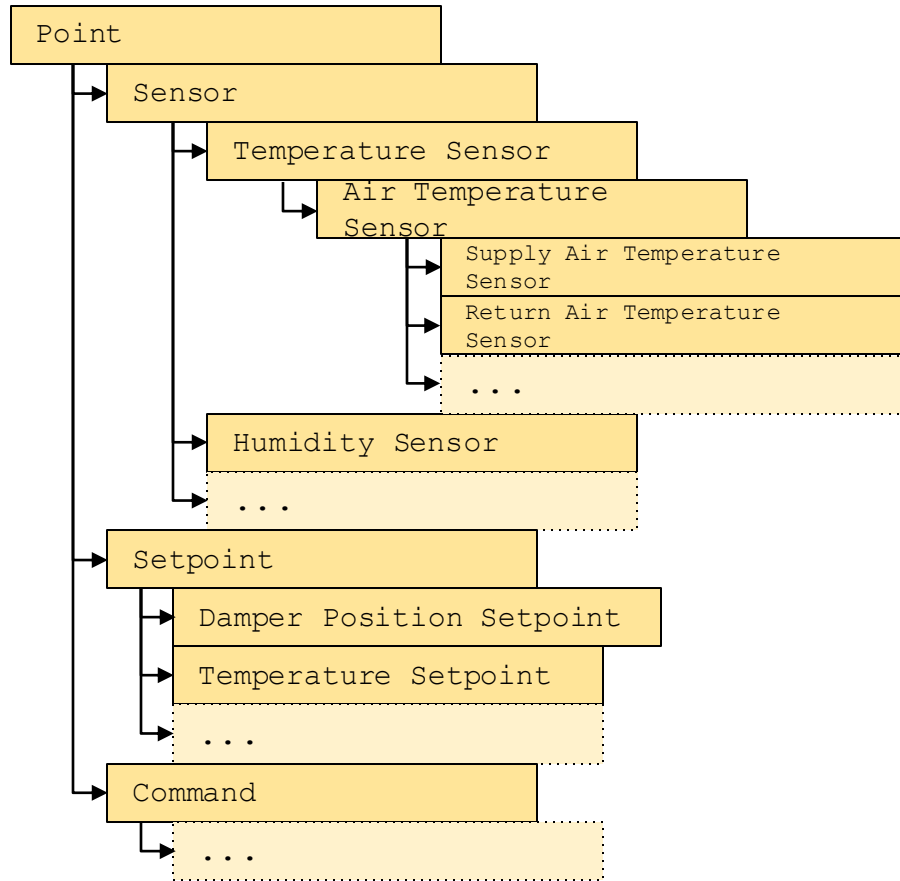
Mechanical Diagrams: human-readable and non-standard



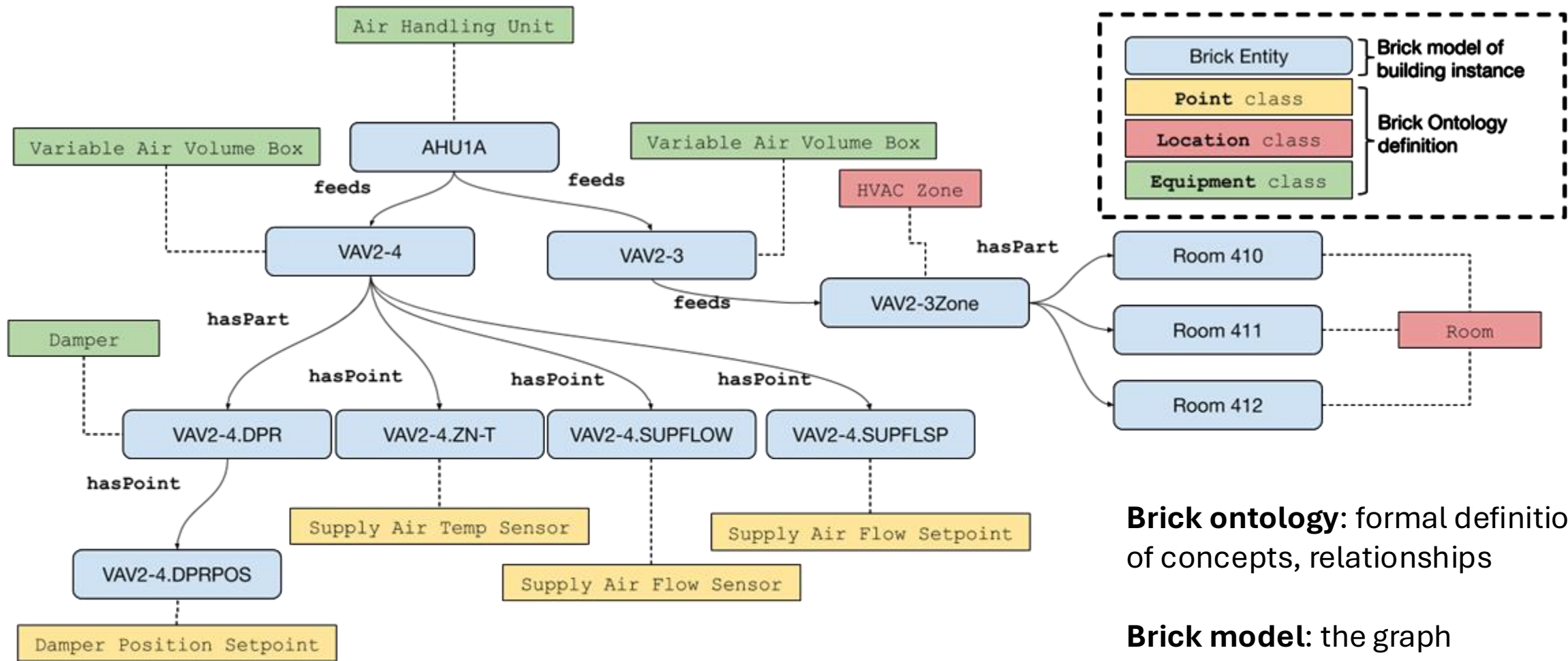
RDF Graphs: standard machine/human-readable models

- Build on **Resource Description Framework (RDF)** W3C standard for directed, labeled graphs
  - Tap into existing open-source and commercial ecosystems of tools
  - Supports sophisticated search and discovery
- **SPARQL**: Standard graph query language
  - Retrieve information from graphs
- **SHACL**: Constraint language for graphs
  - Enable automated validation of models
  - Acts as a “schema” for graphs

# What's in the Ontology?

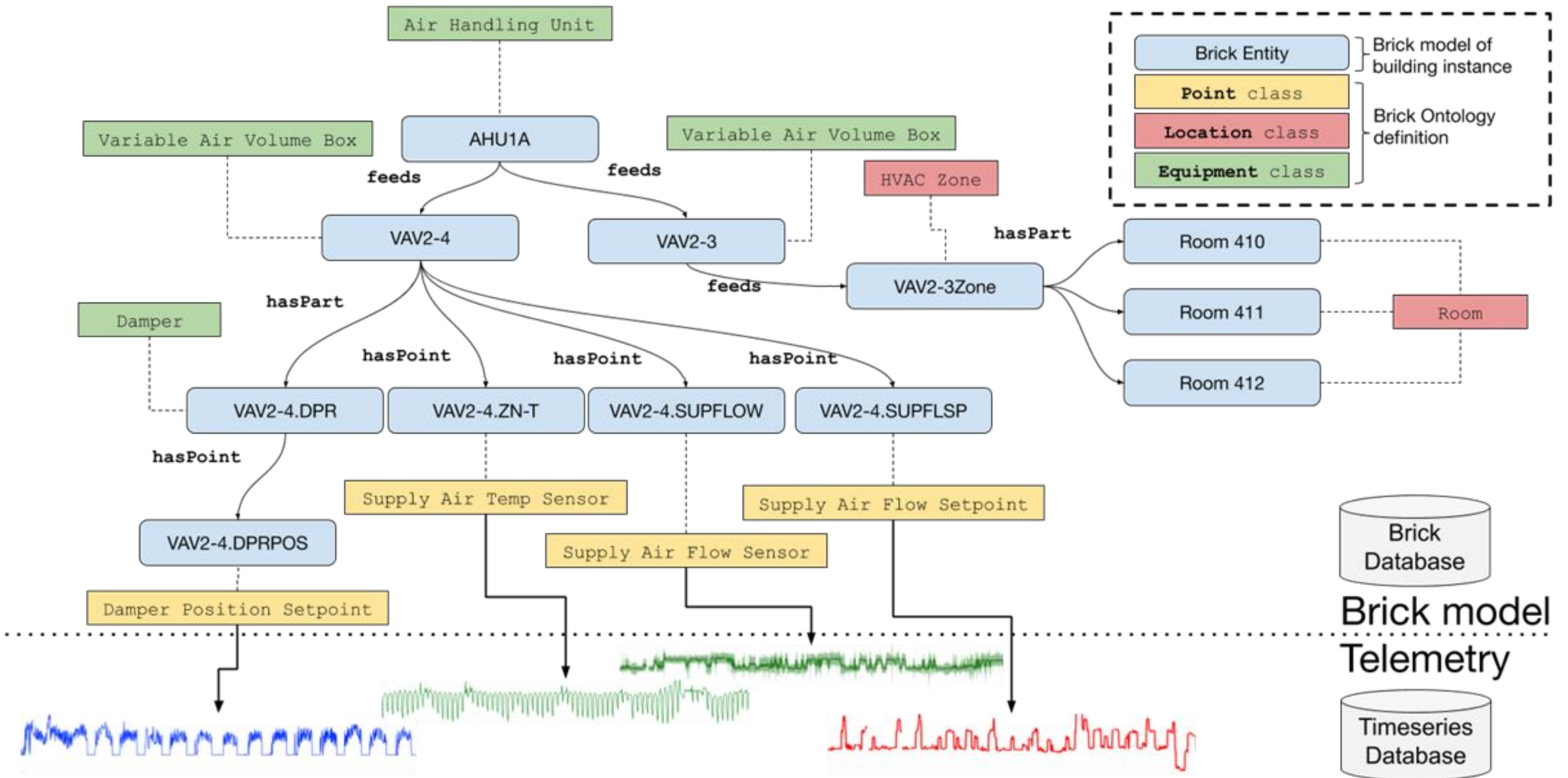


- Class hierarchy covering over 800 major equipment types, architectural elements
- **Point** classes cover different types of I/O data
  - Sensors (r), setpoints (r/w), commands (r/w), alarms (r), statuses (r)...



**Brick ontology:** formal definitions of concepts, relationships

**Brick model:** the graph representing a particular building



- Relate Brick Point instances to timeseries data
- We can now use knowledge graphs for configuring our software

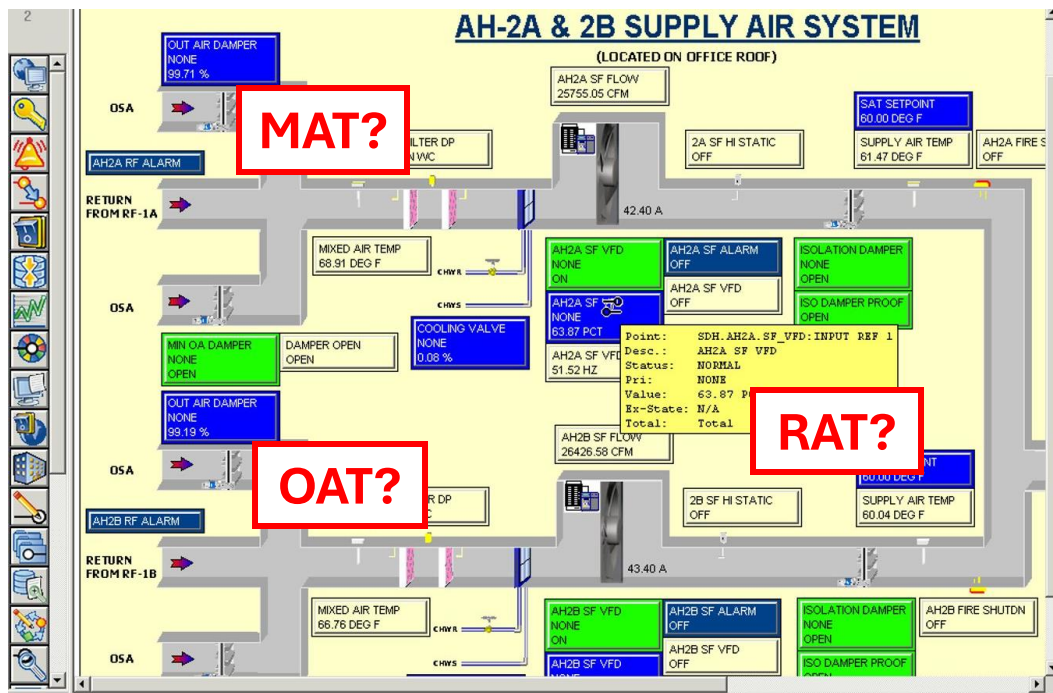
# Portable Cyber-Physical Programming

FC #2 (omit if no MAT sensor)	Equation	$MAT_{AVG} + \epsilon_{MAT} < \min[(RAT_{AVG} - \epsilon_{RAT}), (OAT_{AVG} - \epsilon_{OAT})]$
	Description	MAT too low; should be between OAT and RAT
	Possible Diagnosis	RAT sensor error MAT sensor error OAT sensor error

MAT?  
RAT?  
OAT?

Example Fault Detection Rule:

- Runs on a particular type of asset
- Needs specific sensors
- **Sensors and data sources may have different names, or not be installed**
- Most rule implementations hard code these names



```

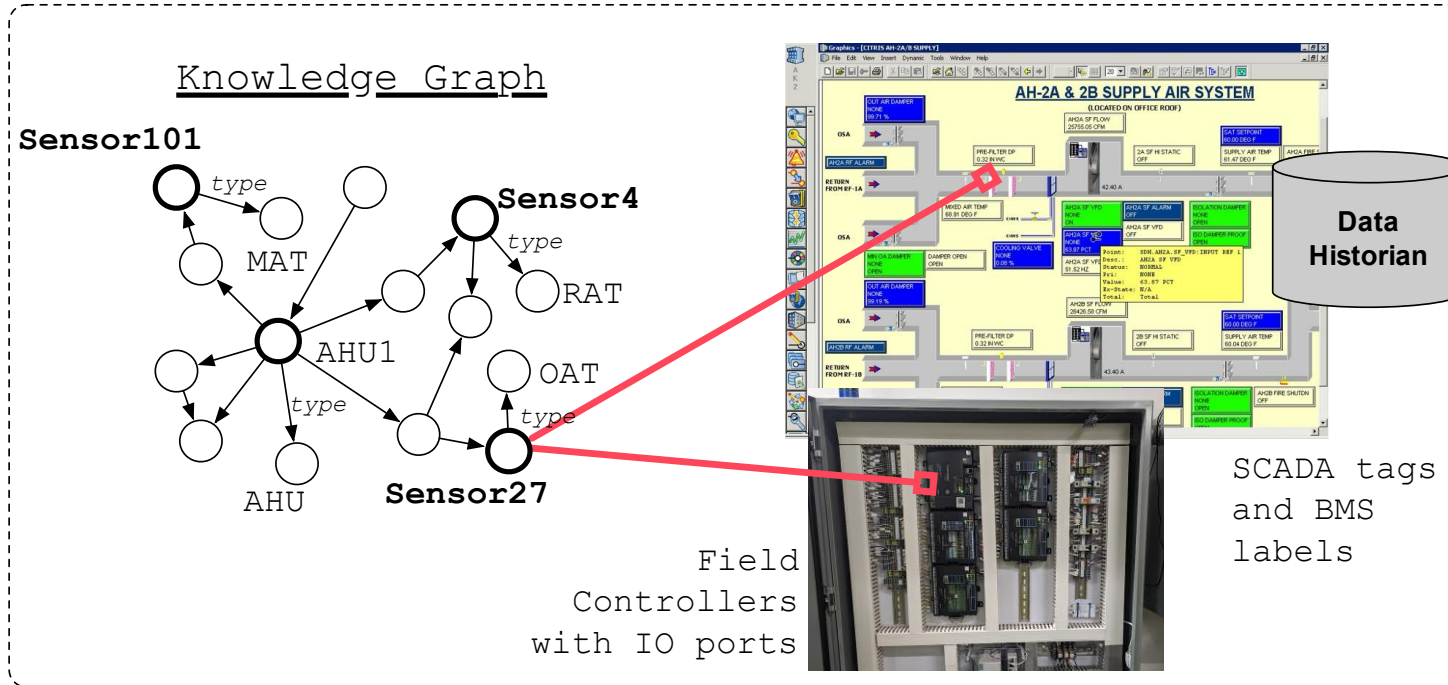
AHU.AHU01.CAV1-1:DMPRPOS
AHU.AHU01.CAV1-1:HTG O
AHU.AHU01.CAV1-1:SUPFLOW
AHU.AHU01.CAV1-1:ZN T
AHU.AHU01.CAV2-1:DAT
AHU.AHU01.CAV2-1:DMPRPOS
AHU.AHU01.CAV2-1:HTG O
AHU.AHU01.CAV2-1:SUPFLOW
AHU.AHU01.CAV2-1:ZN T
AHU.AHU01.CCV
AHU.AHU01.CHWHHW.UNT:CHW FLOW
AHU.AHU01.CHWHHW.UNT:HW FLOW
AHU.AHU01.Cooling Enable
AHU.AHU01.ECM
AHU.AHU01.HP.UNT:ZN T
AHU.AHU01.HSP
AHU.AHU01.LSP
AHU.AHU01.LTD
AHU.AHU01.MAX_ZONE.DAMPER
AHU.AHU01.MAX_ZONE.HEATING
AHU.AHU01.MIN OA
AHU.AHU01.Mixed Air Damper Position
AHU.AHU01.Mixed Air Temp
SODA2S14_SMK
SODA1S11_MAT
SODA3R315_RVAV
SODA3R723_ASO
SODA3R327_AGN
SODH1P02_FLT
SODA3R798_ART
SODA1R405B_ARS
SODA3R683_RVAV
SODA1R405B_ART
SODA3R311_AGN
SODH1_LL
SODC1SP03_FLT
SODA4R645_RVAV
SODA1R288_AGN
SODA3R419_AGN
SODA3C611_ASO
SODA2S14_P_VR
SODA4S1832_STA
    
```

Which variables correspond to

MAT?  
RAT?  
OAT?

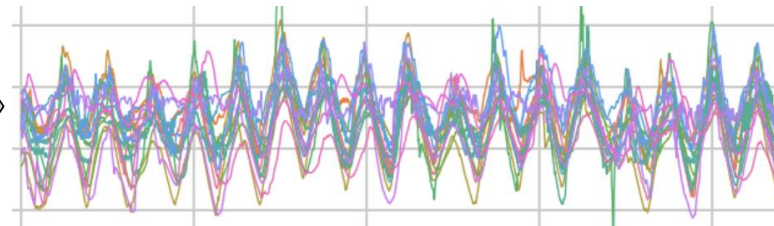
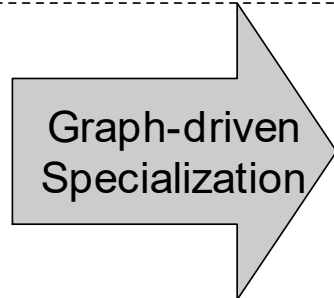
Hundreds of non-standard variable names...

# Portable Cyber-Physical Programming



- Solution: don't use variable names!
- Replace variables with **graph queries**
- System runs the queries to bind variables to the available data sources

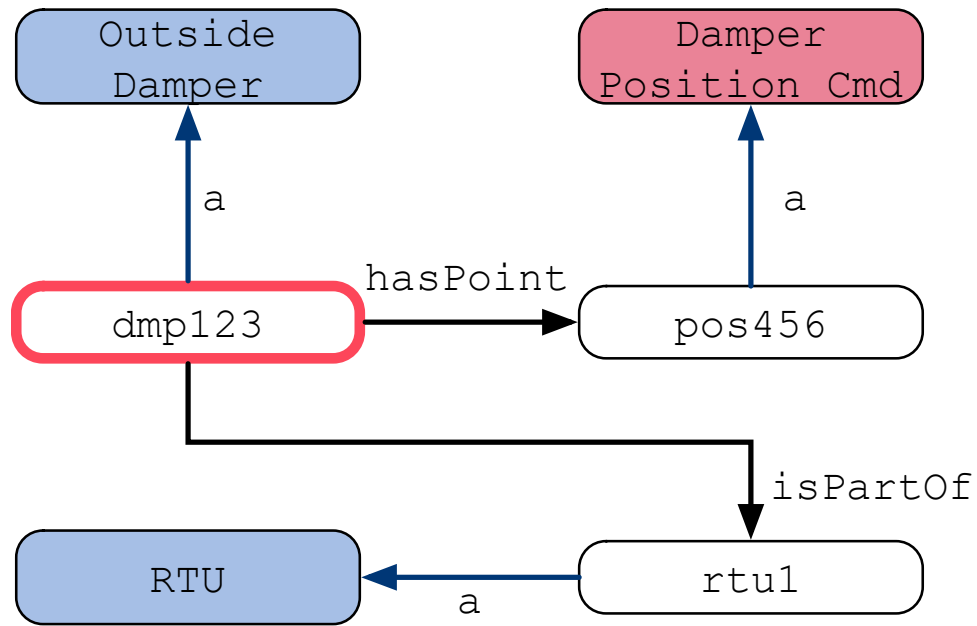
AHU	Air Handling Unit (Equipment)
MAT	Mixed Air Temperature (Sensor)
RAT	Return Air Temperature (Sensor)
OAT	Outside Air Temperature (Sensor)



When  $\{MAT\} < \min(\{RAT\}, \{OAT\})$   
on an  $\{AHU\}$  then raise **error**

When  $\{Sensor101\} < \min(\{Sensor4\}, \{Sensor27\})$   
on  $\{AHU1\}$  then raise **error**

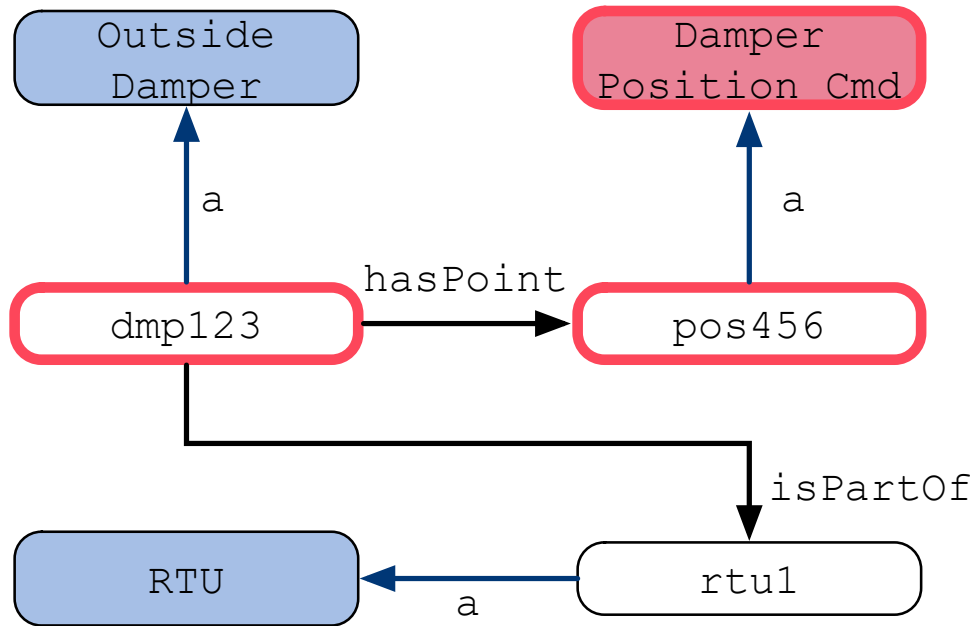
# Graph Queries on Knowledge Graphs



```
SELECT * WHERE {  
  ?x a brick:Outside_Damper .  
}
```

- Pattern matching on *node-edge-node* **triples**
- ?variables bind to the missing parts of the pattern
- Share variables to JOIN different patterns
- Common patterns:
  - **Find instances of a type** (or supertype)
  - Relate instances of different types together

# Graph Queries on Knowledge Graphs



```
SELECT * WHERE {  
  ?x a brick:Outside_Damper .  
  ?x brick:hasPoint ?p .  
  ?p a ?point_class  
}
```

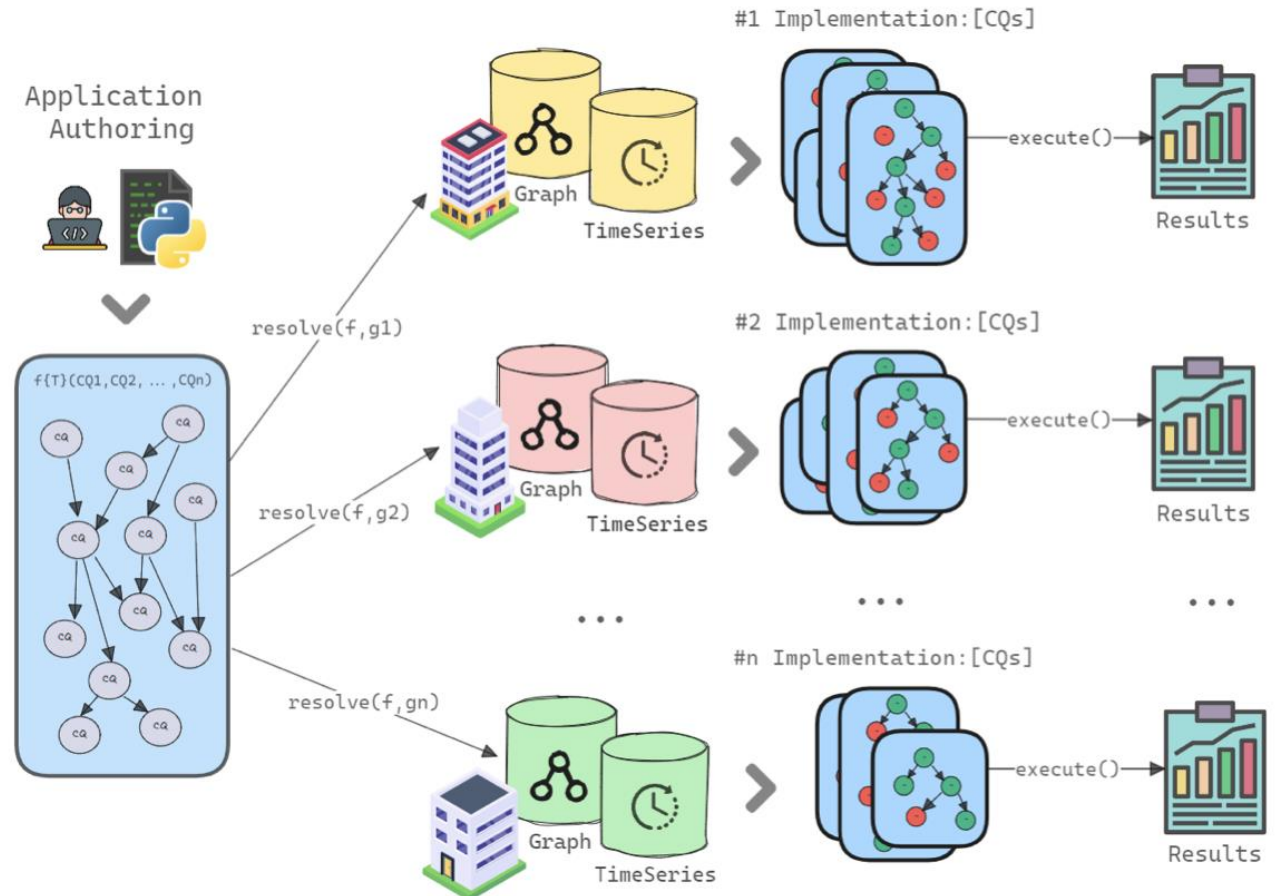
- Pattern matching on *node-edge-node* **triples**
- ?variables bind to the missing parts of the pattern
- Share variables to JOIN different patterns
- Common patterns:
  - Find instances of a type (or supertype)
  - Relate instances of different types together

# SeeQ: New Programming Model for CPS Code

- Write Python applications against concepts defined by knowledge graph
- SeeQ “compiles” the Python code against the metadata model for each building
  - Generates site-specific implementation

```

1 from SeeQ import *
2 from pandas import DataFrame
3 from G36.CQs import Dmp_Pos, Fsa, Fsp_clg, Fan_s
4 from APAR.CQs import Tsa, Tma, DelTsf, Hc_pos, Epsilon_t
5
6 def APAR_R1(sup: Tsa, mix: Tma, drop: DelTsf, heat_coil: Hc_pos, e: Epsilon_t):
7     is_heating: DataFrame = heating_coil.df > 0
8     supply_air_low: DataFrame = sup.df < (mix.df + drop.df - error.df)
9     violating_records = is_heating & supply_air_low
10    # returns fault if more than 10 violating samples
11    if len(violating_records) > 10:
12        return "fault detected"
13
14 def G36_Dmp_Leaking(pos: Dmp_Pos, sup_flow: Fsa, cool_sp: Fsp_clg, fan: Fan_s):
15     if ((pos.df == 0) and (sup_flow.df > max([0.1*cool_sp.df, 50]) \
16         and (fan.df == "ON")).for_time(600):
17         return "Level 4 alarm"
    
```

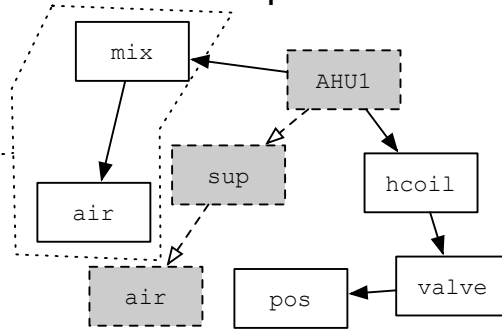


# Portable Programming Model

## Original Rule

```
def rule1(ahu) -> bool:
    is_heating = ahu.hcoil.valve.pos > 0
    if not is_heating: return False
    sup_air_temp = ahu.sup_air.temp
    mix_air_temp = ahu.mix_air.temp
    fan_temp_drop = 1.1 # degC, approx
    eps = 0.1
    return sup_air_temp < mix_air_temp +
           fan_temp_drop - eps
```

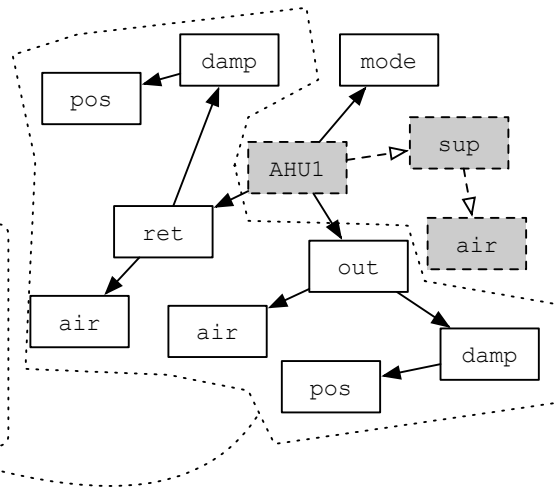
## Graph A



## Specialized Implementation

```
def rule1(ahu) -> bool:
    # !! Different detection of heating mode
    is_heating = ahu.hvac_mode == 'heating'
    if not is_heating: return False
    sup_air_temp = ahu.sup_air.temp
    # approximate mixed air with available sensors
    ret_damper_pos = ahu.ret_damper.pos
    out_damper_pos = ahu.out_damper.pos
    ret_air_temp = ahu.ret_air.temp
    out_air_temp = ahu.out_air.temp
    mix_air_temp = ret_air_temp * ret_damper_pos +
                  out_air_temp * out_damper_pos
    fan_temp_drop = 1.1 # degC, approximated
    eps = 0.1
    return sup_air_temp < mix_air_temp +
           fan_temp_drop - eps
```

## Graph B



- Compiled Python code detects different subgraphs
- Adjusts data discovery and application logic automatically
- Generate **site-specific** implementations with zero human configuration

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	Possible Diagnosis	RAT sensor error MAT sensor error OAT sensor error

# Encoding Application Requirements

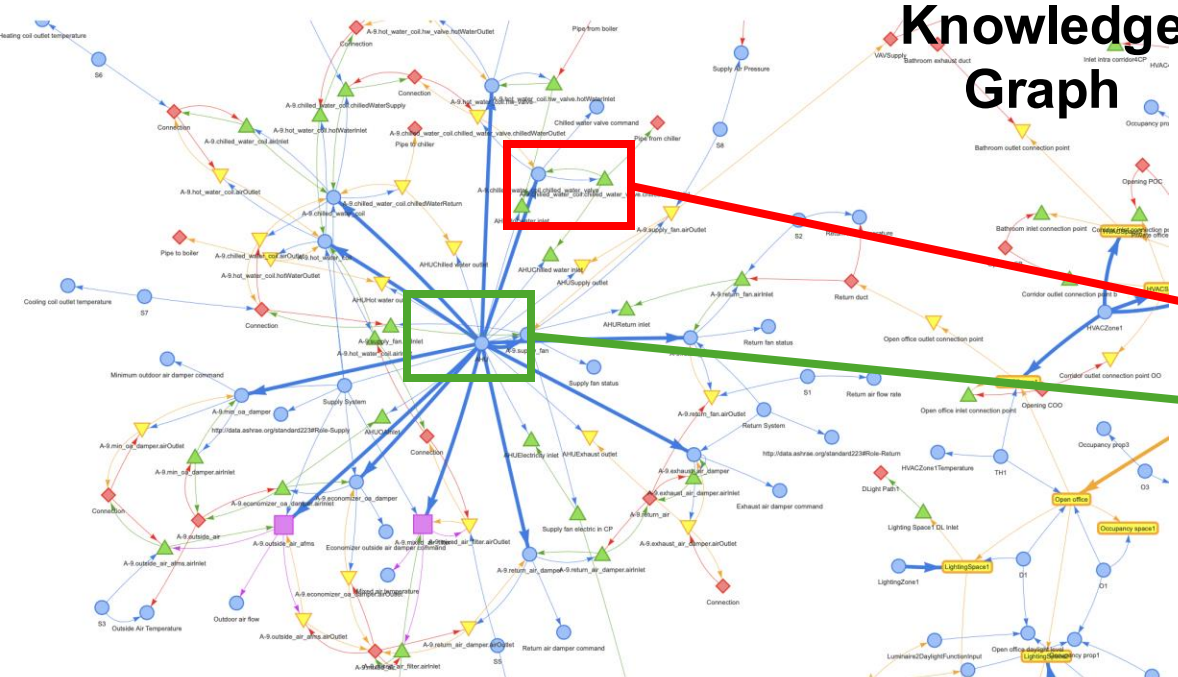
## 4.2 VAV Terminal Unit with Reheat

Required?	Description	Type	Device
R	VAV box damper position	AO OR two DOs	Modulating actuator OR Floating actuator
R	Heating signal	AO OR two DOs	Modulating valve OR Floating actuator OR Modulating electric heating coil
R	Discharge airflow	AI	DP transducer connected to flow sensor
R	Discharge air temperature (DAT)	AI	Duct temperature sensor (probe or averaging at designer's discretion)
R	Zone temperature	AI	Room temperature sensor
A	Local override (if applicable)	DI	Zone thermostat override switch
A	Occupancy sensor (if applicable)	DI	Occupancy sensor
A	Window switch (if applicable)	DI	Window switch
A	Zone temperature setpoint adjustment (if applicable)	AI	Zone thermostat adjustment
A	Zone CO <sub>2</sub> level (if applicable)	AI	Room CO <sub>2</sub> sensor

- Come in many different forms...
- **At right:** point lists from ASHRAE Guideline 36
- Required I/O points for a high-performance control sequence
- How to ensure Brick model contains the right metadata?

- **Validate** the knowledge graph against application requirements
- Report lists which parts of the building support which applications

### Building Knowledge Graph



#### 4.2 VAV Terminal Unit with Reheat

Required?	Description	Type	Device
R	VAV box damper position	AO OR two DOs	Modulating actuator OR Floating actuator
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R	Zone temperature	AI	Room temperature sensor
A	Local override (if applicable)	DI	Zone thermostat override switch
A	Occupancy sensor (if applicable)	DI	Occupancy sensor

### Application Data Requirements



SHACL Validation Process

Shapes validate KG content



- Use validation results to fix the knowledge graph (support more apps!)

FCU503	Passes Validation
FCU510	<b>Fails Validation:</b> <ul style="list-style-type: none"> <li>- missing Room Air Temp Sensor</li> <li>- missing Heating Coil</li> <li>- missing Filter</li> </ul>

### Validation Report

# Using Validation to Fix a Knowledge Graph

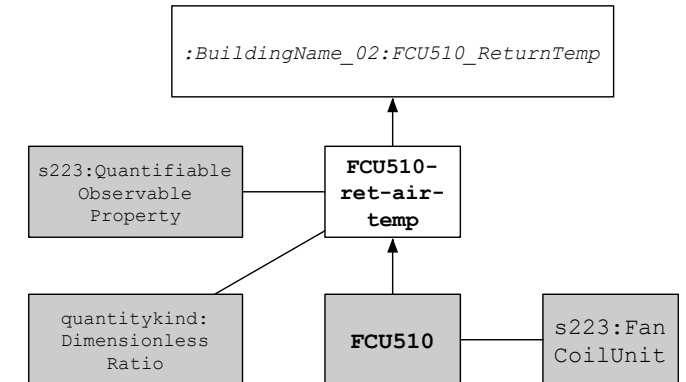
From validation process



FCU503	Passes Validation
FCU510	<b>FAILS Validation:</b> <ul style="list-style-type: none"><li>- missing Room Air Temp Sensor</li><li>- missing Heating Coil</li><li>- missing Filter</li></ul>

**Validation Report**

To validation process



**Model Patch**

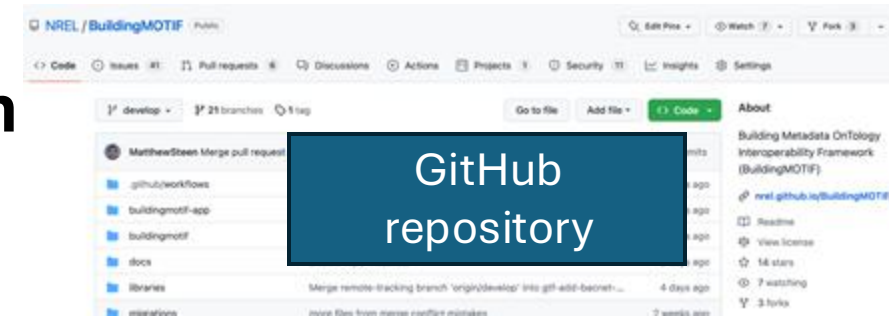
## Possible fixes

- Extend point label naming convention script
- Re-scan network for more points
- Extract metadata from BIM
- Prompt user for specific inputs

# BuildingMOTIF SDK

- **KG construction, validation + App configuration**

- Available on GitHub under NREL organization
- Released under permissive BSD 3 Clause license
- Tutorials, notebooks, demo web interface
- Supports Brick and other ontologies
- *Simplifies building metadata-driven software*



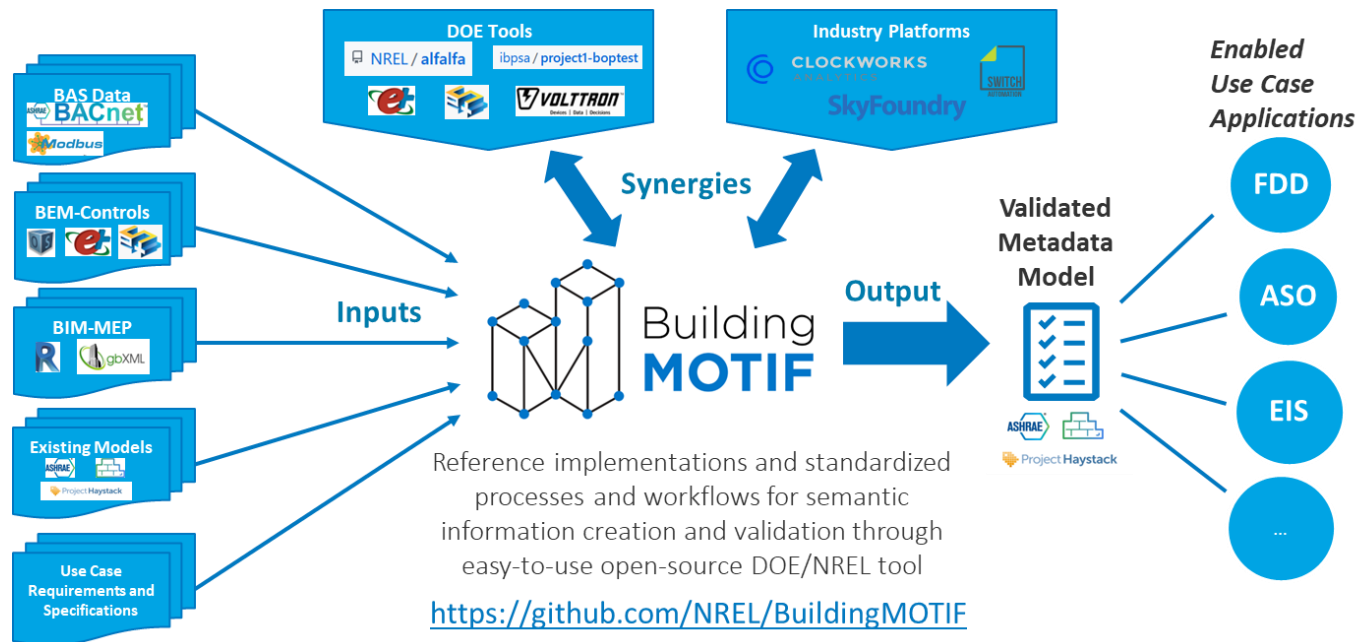
## Application-Driven Creation of Building Metadata Models with Semantic Sufficiency

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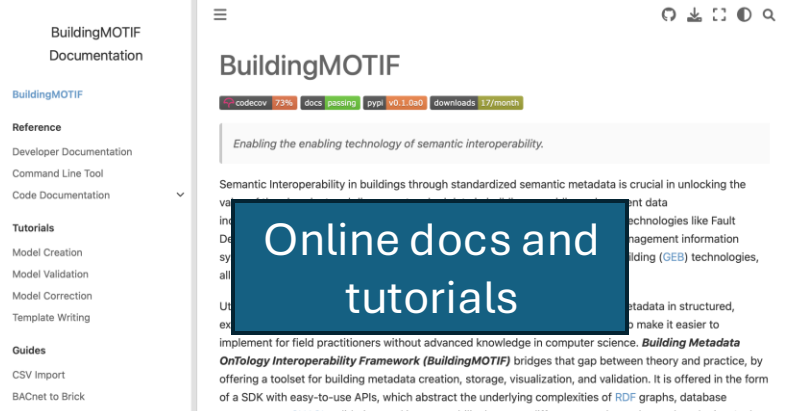
Tobias Shapinsky  
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National Renewable Energy  
Laboratory  
Golden, Colorado, U.S.A.

Research papers  
on internals



**ABSTRACT**  
Semantic metadata models such as B...  
Haystack, and BOT promise to simplify and lower the cost of de-  
veloping software for smart buildings, enabling the widespread  
deployment of energy efficiency applications. However, creating  
these models remains a challenge. Despite recent advances in cre-  
ating models from existing digital representations like point labels

Estinger. 2022. Application-Driven Creation of Building Metadata Models  
with Semantic Sufficiency. In *The 9th ACM International Conference on  
Systems for Energy-Efficient Buildings, Cities, and Transportation (BuildSys  
'22)*, November 9–10, 2022, Boston, MA, USA. ACM, New York, NY, USA,  
19 pages. <https://doi.org/10.1145/3563357.3564083>



# Thank you!

- My current research/projects: <https://gtf.fyi>
  - Contains links to all the works I've mentioned in this talk
  - Most have an open-source GitHub repository associated with them
- Brick ontology project: <https://brickschema.org>
- ASHRAE 223P development: <https://open223.info>
  - new smart building ontology!
- NREL-developed semantic metadata platform: <https://github.com/NREL/BuildingMOTIF>